



Research Paper

Advancing Sugarcane Farm Management Through NDVI-Based Color Mapping and Drone Imaging

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Abstract

Precision agriculture has emerged as a key strategy for boosting crop productivity and optimizing resource use. This study leverages advanced imaging and machine learning to enhance the management of sugarcane farms. Using drones, high-resolution RGB images of sugarcane fields are captured and transformed into multispectral images through a Generative Adversarial Network (GAN), revealing critical spectral data for plant health assessment. The Normalized Difference Vegetation Index (NDVI) is derived from these multispectral images and serves as a vital measure of vegetation health. This NDVI data, combined with farmer-reported yield information, creates a comprehensive dataset linking NDVI values to actual crop yields. To predict sugarcane yield from NDVI values, we trained a feedforward neural network on this integrated dataset. The proposed method not only enhances prediction accuracy but also provides valuable insights into the connection between NDVI metrics and crop performance. The model was validated using individual field images, enabling precise yield predictions for different field sections. This study highlights the effectiveness of integrating drone imagery, machine learning, and remote sensing in precision agriculture. The combination of NDVI data with yield information provides a robust tool for optimizing sugarcane production, improving farm management decisions, and advancing agricultural sustainability.

Keywords: NDVI (Normalized Difference Vegetation Index); Multispectral Imaging; Generative Adversarial Networks (GANs); Crop Yield Prediction.

INTRODUCTION

Precision agriculture represents a revolutionary shift in modern farming that leverages cutting-edge technologies to optimize productivity, sustainability, and resource management. At the core of this innovation lies multispectral imaging, a powerful tool that can capture data beyond the visible spectrum. This technology provides crucial insights into plant health, growth conditions, and environmental factors by detecting details such as chlorophyll levels, nutrient deficiencies, and early signs of disease or stress that are not visible with standard RGB (red, green, blue) imaging. These insights enable farmers to make informed decisions about irrigation, fertilization, and pest control, leading to increased crop yields and more efficient use of resources.

Sugarcane cultivation particularly benefits from multispectral imaging. As a long-cycle crop that requires continuous monitoring from planting to harvest, sugarcane farming can be labor-intensive when traditional methods are used. Multispectral imaging streamlines this process by providing frequent high-resolution data, thereby allowing early detection of potential issues. For instance, it can identify variations in plant health across a field, highlighting areas that may require additional nutrients or are affected by pest infestations. This targeted approach not only minimizes yield loss but also optimizes resource allocation, reducing the environmental impact of excessive fertilizer or pesticide use.

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The introduction of drones equipped with multispectral sensors has further revolutionized precision agriculture. These drones can efficiently survey large areas and capture detailed images to assess crop conditions in real time. Comprehensive, high-resolution data gathered from drones offer a panoramic view of the entire farm, allowing farmers to monitor growth patterns, detect anomalies, and implement targeted interventions. This proactive strategy enhances crop health while promoting sustainable practices by minimizing resource overuse. Despite these numerous benefits, the high cost of multispectral sensors remains a challenge, particularly for small- to medium-scale farmers.

To address this challenge, researchers are exploring the use of artificial intelligence (AI), specifically, generative adversarial networks (GANs), to convert standard RGB images into multispectral data. Group with GAN are advanced AI models that generate high-quality synthetic data by learning from existing datasets. By training these networks on paired RGB and multispectral images, models can be developed to predict multispectral information accurately from standard RGB inputs. This innovation significantly reduces costs because it eliminates the need for specialized sensors while still delivering valuable analytical insights. Synthetic multispectral images generated through this process can be analyzed using the same methods as traditional multispectral data, providing farmers affordable access to advanced crop health diagnostics.

The integration of multispectral imaging, drone technology, and AI is transforming agricultural practices by making them more efficient, sustainable, and data-driven. This combination enables continuous crop monitoring, early problem detection, and precision interventions, all of which contribute to higher productivity and reduced environmental impact. For sugarcane farmers, these technologies offer an effective way to manage the complexity of long-cycle crop. By ensuring that resources are allocated efficiently and yield potential is maximized, this approach mitigates the challenges associated with traditional farming methods.

Looking ahead, the future of precision agriculture appears to be promising. As advancements in AI and drone technology continue to evolve, these tools are becoming more accessible, benefiting farmers across various scales. The democratization of multispectral imaging through cost-effective AI solutions can revolutionize crop monitoring and management globally. By harnessing these technologies, farmers can not only enhance productivity but also contribute to a more sustainable and resilient agricultural sector. This shift toward data-driven farming practices marks a significant milestone in modern agriculture, offering hope for improved food security, resource management, and environmental conservation in the years to come.

LITERATURE REVIEW

The integration of RGB and multispectral imaging has revolutionized agricultural yield prediction, particularly for sugarcane, by enhancing the accuracy of forecasts through advanced techniques like NDVI (Normalized Difference Vegetation Index) and machine learning. NDVI has proven effective in predicting yields across different crops, including millet and sorghum in Africa ([Maselli et al., 2000](#)) and corn in the United States. The Corn Belt ([Ji et al., 2021](#)), combined with multispectral data, provides deeper insights into crop health and growth. Precision agriculture (PA), which utilizes technologies like UAVs and remote sensing, optimizes resource use and improves yield forecasting. PA could increase sugarcane yields in India by 20%–40%, potentially reaching 100–110 Mg ha⁻¹ by 2030 ([Carrer et al., 2022](#)), by integrating early-season forecasting with data-driven decision-making ([Han et al., 2022](#)). UAVs equipped with RGB and multispectral sensors offer high-resolution images, improving yield estimations by capturing key variables like stalk height and density ([Huang et al., 2024](#)). Techniques like Conditional Generative Adversarial Networks (CGANs) are also being employed to convert RGB images into multispectral images, providing a cost-effective alternative to traditional multispectral sensors ([Rodríguez-Suárez et al.,](#)

2022), with improved spectral accuracy. This transition from RGB to multispectral imaging, combined with temporal data collection and machine learning, holds great promise for sugarcane yield prediction, enabling more precise and efficient agricultural management. Advancing sugarcane farm management through NDVI-based color mapping and drone imaging integrates remote sensing technologies to improve crop monitoring and management practices. NDVI derived from drone imagery provides precise assessments of crop health, growth, and yield potential, leading to enhanced agricultural efficiency. NDVI and drone imaging play key roles in sugarcane management by aiding in weed control, where NDVI effectively differentiates between sugarcane and weeds, creating site-specific prescription maps for targeted herbicide use and improved profitability (Romero & Heenkenda, 2024). UAVs equipped with RGB cameras also allow for the monitoring of crop growth, with NDVI helping to predict plant height and growth patterns and improving crop management strategies (Ruwanpathirana et al., 2024). Additionally, aerial phenotyping using NDVI facilitates the rapid identification of high-yielding genotypes, supporting better breeding strategies and drought tolerance assessments (Hoffman et al., 2024; Khuimphukhio et al., 2024). While promising, challenges remain in correlating NDVI with traditional management zones, highlighting the need for further refinement in methodologies to enhance precision agriculture practices (Maia et al., 2022).

RESEARCH METHOD

Data Acquisition

The integration of drone-based data acquisition for sugarcane yield prediction has become a game-changer, improving both accuracy and efficiency in modern agricultural management. By using unmanned aerial vehicles (UAVs), high-resolution images can be captured and analyzed to derive key metrics related to yield prediction. This approach surpasses the limitations of traditional satellite imagery by providing timely and detailed data that are critical for informed decision-making in agriculture.

UAV Imagery and Yield Estimation

UAVs equipped with RGB and multispectral sensors provide highly detailed images of sugarcane fields. These images facilitate the estimation of important allometric variables such as stalk height and density, which are essential for yield prediction (Huang et al., 2024). Research has shown that combining UAV data with machine learning models can produce intra-field yield maps with an impressive root mean square error (RMSE) as low as 6.88 t/ha, illustrating the high spatial variability in sugarcane yields (Som-ard et al., 2024).

Quality Prediction and Machine Learning

The integration of multispectral images with machine learning algorithms has proven successful in predicting sugarcane quality indicators such as °Brix and Purity, achieving more than 80% accuracy in many cases (Júnior et al., 2023). Moreover, hyperspectral imaging enhances the accuracy of yield prediction by allowing precise genotype selection based on key yield-related components (Poudyal et al., 2022).

High-throughput phenotyping

Drone technology enables high-throughput phenotyping, which is vital for breeding programs. By correlating canopy features with yield metrics, UAV can improve selection efficiency and expedite the breeding process (Khuimphukhio et al., 2023). While this technology significantly boosts the accuracy of yield prediction, it still faces challenges, such as the need for extensive field data to train predictive models and the relatively high operational costs of UAV deployment.

Nevertheless, the advantages of timely and precise yield estimation highlight the growing importance of UAVs in modern agricultural practices.

In this research, we used a DJI Phantom 4 drone equipped with an RGB camera to capture a comprehensive set of high-resolution images—up to 5,000 images in total—across multiple sugarcane farms. The drone was consistently flown at a fixed altitude, ensuring that all captured images had the same scale, resolution, and perspective. This consistency minimizes variations that could otherwise arise from changes in flight height, which is critical for temporal and spatial comparisons.

A key feature of our data collection process was age-wise image capture, conducted at regular intervals of 2–3 months, starting from 2 months and continuing until 17 months of the sugarcane growth cycle. The images were captured from a sugarcane farm at Ambe village (Pandharpur, India), spanning an area of up to 30 acres. Drone flights over the field were conducted between 11 AM and 2 PM on the following dates: November 2022 to the present. We photographed the same farms at various stages of crop growth, beginning with the initial planting phase and continuing through to harvest. By capturing images at different points in the crop's lifecycle, we can observe and track the visual changes in sugarcane plants over time. This age-based approach is essential for monitoring the development of crops and how their appearance and health indicators, such as NDVI, evolve as plants mature.

The dataset comprises a broad spectrum of images representing different growth stages and environmental conditions across farms. This extensive collection of images enhances the robustness of our yield prediction models, enabling more accurate predictions by integrating both visual data (RGB images) and calculated NDVI values. This method provides a more holistic understanding of the correlation between crop development and yield outcomes.

Furthermore, this large-scale dataset strengthens our ability to analyze the variables influencing yield, offering more comprehensive insights into sugarcane growth patterns. If necessary, sample images from the dataset can be provided for further analysis or collaboration, ensuring the applicability of the data to other related research.

By combining consistent drone-based image capture and temporal tracking, we created a strong foundation for modeling and predicting crop yield with improved precision. This process not only supports the NDVI analysis but also provides a wealth of visual information to enhance the accuracy of the yield predictions.

Conversion of RGB to Multispectral Images

A robust approach for converting RGB images to multispectral images (MSIs) can be developed by integrating various advanced techniques from recent studies. The conversion of RGB images to multispectral images using Conditional Generative Adversarial Networks (CGANs) has gained traction in remote sensing and image processing because of its innovative approach to solving inherent challenges. By leveraging adversarial training, CGANs can produce high-quality multispectral images from RGB data, thereby addressing the complexities of the conversion process. The following overviews the key aspects of this methodology:

CGAN Architecture and Functionality

CGANs consist of two key components: a generator that is responsible for creating multispectral images and a discriminator that assesses the authenticity of the generated images against real multispectral data. The generator is conditioned on the RGB input, enabling it to learn

the mapping from RGB to the multispectral domain efficiently, as demonstrated by [Rodríguez-Suárez et al. \(2022\)](#) and [Lore et al. \(2019\)](#).

Performance and Results

CGANs significantly enhance the spectral accuracy. For example, using a ResNet-based generator, a CGAN achieved a root mean square error (RMSE) of 316 in multispectral image reconstruction ([Rodríguez-Suárez et al., 2022](#)). Moreover, the integration of Variational Autoencoders (VAEs) has further improved the quality of generated images by mitigating information loss during the reconstruction process ([Liu et al., 2021](#)).

Applications and Implications

The ability to convert RGB to multispectral data using CGANs has a wide range of applications, particularly in fields like remote sensing, agriculture, and environmental monitoring, where multispectral information is vital for informed decision-making ([Liu et al., 2021](#)). Furthermore, this technology helps reduce the cost associated with acquiring specialized multispectral imaging equipment, making advanced imaging techniques more accessible to a broader audience ([Rodríguez-Suárez et al., 2022](#)).

CGANs offer significant potential in RGB-to-multispectral conversion; however, ensuring high fidelity across various spectral bands remains a challenge. In future work, we will refine these models to improve their robustness and adaptability in diverse practical applications.

GAN Framework for Multispectral Reconstruction

VAE-GAN Approach: This method merges Variational Auto encoders (VAEs) with Generative Adversarial Networks (GANs), enabling effective reconstruction of multispectral images (MSIs) from RGB images. The VAE component samples from a Gaussian distribution to estimate the missing spectral information, and the GAN ensures that the generated output closely resembles the true multispectral data ([Liu et al., 2021](#)). As shown in Figure 1, the ResNet-based generator significantly enhances the learning capacity of the model by effectively capturing intricate features in the data.

Multi-Code GAN Prior: This technique uses multiple latent codes to generate diverse feature maps, which enhances the accuracy of the reconstructed MSIs from RGB data. The over-parameterization in this model improves the fidelity and detail of the output ([Gu et al., 2020](#)).

Data Preparation and Training Techniques

Patch-Based Learning: Small overlapping patches are extracted from RGB images and aligned with hyperspectral training patches. The proposed method capitalizes on spatial correlations to recover detailed spectral information ([Akhtar & Mian, 2018](#)).

Unsupervised Domain Adaptation: The use of ColorMapGANs aligns the spectral distribution of the training images with that of the test images, making the model more robust to variations in spectral data and improving generalizability ([Tasar et al., 2020](#)).

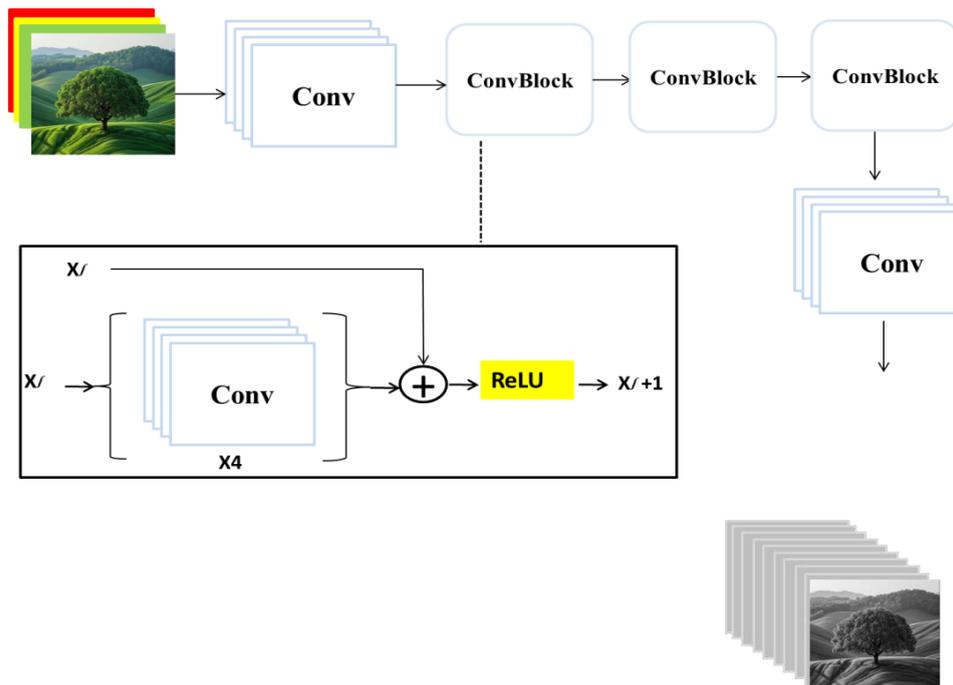


Figure 1. Res-net-based generator

Creating Our Own Multispectral Images After GAN Processing

After using Generative Adversarial Networks (GANs) to convert RGB images into multispectral images, the next step was to generate multispectral images for deeper agricultural analysis. Once trained on RGB inputs, the GAN model synthesizes multispectral images that capture spectral details beyond the visible spectrum. These synthesized images are crucial for deriving important vegetation indices like NDVI (Normalized Difference Vegetation Index) and for linking spectral data to crop yield predictions.

The process of generating multispectral images

Once the GAN has learned how to map RGB images to multispectral representations, we pass the collected RGB images through the trained network. The GAN then generates multiple spectral bands from each RGB image, allowing us to obtain key information such as

1. **Visible- Spectrum Bands (RGB):** These are the standard red, green, and blue channels found in regular images.
2. **Near-Infrared (NIR) Band:** Essential for vegetation analysis, especially when calculating NDVI, which measures plant health by comparing red and near-infrared reflectance.
3. **Additional Bands:** Depending on the specific model setup, the GAN may also generate other spectral bands, such as those in the short-wave infrared (SWIR) range, which can provide further insights into crop conditions.

Benefits of Generating Multispectral Images

Enhanced Data for Precision Agriculture: Multispectral imagery provides access to a broader spectrum of data than standard RGB images. Additional bands, particularly the NIR band, are essential for calculating NDVI, which is a key metric used in agriculture to assess plant health and vigor. Generating these multispectral images allows us to track and analyze crop conditions more accurately, leading to better yield predictions. **Customization and Control:** Generating multispectral images allows us to tailor the spectral bands to specific research needs. For instance, we can focus on the spectral information most relevant to sugarcane crops, thus optimizing our

ability to assess crop health and predict yield. By converting existing RGB images into multispectral images, we maintain flexibility and control over the data without requiring additional hardware for new multispectral captures. **Cost Efficiency:** Traditional multispectral cameras are expensive and may limit the number of bands they capture. By using group with GAN to generate multispectral images from standard RGB inputs significantly reduces the costs associated with acquiring specialized equipment while obtaining the spectral insights necessary for analysis. **Consistency Across Data Sets:** We used the same RGB images captured by the DJI Phantom 4 drone for multispectral generation; thus, we ensure consistency across the entire dataset. This is particularly valuable when performing time series analysis or comparing different farms. It also prevents the need to re-capture images with multispectral cameras, saving time and resources.

Generated Multispectral Images for Analysis

Once the multispectral images are generated, they can be exploited in various advanced agricultural applications:

1. **NDVI Calculation:** With the red and NIR bands in the generated images, we can compute the NDVI for each farm area. NDVI is a widely used index in agriculture that provides a measure of vegetation health by comparing the reflection of red light (absorbed by plants) and NIR light (strongly reflected by healthy vegetation).
2. **Yield Prediction Models:** The calculated NDVI values can be integrated with actual yield data collected from farmers to train predictive models. For instance, using machine learning techniques like feedforward neural networks, we can develop models that predict crop yield based on multispectral inputs and NDVI values.
3. **Temporal monitoring and analysis: Because** we captured age-wise images of the same farms at different stages of growth—we can track changes in NDVI and other vegetation indices over time. This helps explain how the health and productivity of the crop evolve across its lifecycle and how these changes influence final yield.

NDVI Calculation

The Normalized Difference Vegetation Index (NDVI) is a vital index used in remote sensing to evaluate the condition and vitality of vegetation. This index is based on the distinct reflectance properties of crops, particularly their capability to reflect near-infrared (NIR) light while absorbing visible red light. NDVI is widely used in agricultural research for monitoring plant health, estimating yield potential, and assessing overall crop conditions.

NDVI Formula

The NDVI was calculated using the following formula:

$$NDVI = \frac{NIR - R}{NIR + R} \dots (1)$$

Where:

NIR: near-infrared spectrum

R: Reflectance value in the red band

Steps for NDVI Calculation

1. **Data Collection:** Reflectance values were collected from both the NIR and red spectral bands obtained from multispectral imagery.

2. **Application of the NDVI Formula:** The reflectance values are substituted into the NDVI formula to compute the NDVI for each pixel in the image.
3. **Result Interpretation:** The computed NDVI values were analyzed to assess the health and status of the vegetation.

Understanding NDVI Values

NDVI values can range from -1 to +1, with specific ranges indicating different conditions of the vegetation:

1. **NDVI < 0:** This typically indicates non-vegetated areas, such as bodies of water, bare soil, or urban infrastructure.
2. **NDVI \approx 0:** sparse or stressed vegetation, which may indicate health issues or insufficient moisture.
3. **NDVI 0.2 - 0.5:** Represents moderate vegetation health, suggesting that growth is present but not optimal.
4. **NDVI 0.6 - 0.8:** Corresponds to robust and healthy vegetation, indicating favorable growth conditions.
5. **NDVI > 0.8:** Often seen in very dense and thriving vegetation, reflecting excellent health and vigor.

Applications of NDVI

Crop Health Monitoring: The NDVI is an essential tool for farmers and agronomists to continuously assess the state of crops during different growth stages, which aids in making informed decisions regarding irrigation, fertilization, and pest control. **Yield Prediction:** By establishing correlations between NDVI values and historical yield data, researchers can develop predictive models that estimate future crop yields based on current health indicators. **Drought assessment:** The NDVI is a valuable metric for identifying areas affected by drought, as it can reveal stressed or wilting crops, thereby allowing for timely management interventions.

Integrating NDVI and Yield Values to Train Forward Feed Networks

Training a feedforward neural network to predict crop yield based on NDVI values involves a systematic approach to ensure that the model can learn the relationships between these datasets. The process includes careful data preparation, feature engineering, and model development, with the goal of producing accurate yield predictions from the NDVI data.

Taining and testing the neural network

Feedforward network structure

A feedforward neural network was chosen for this task because it can model complex, nonlinear relationships between input variables (NDVI data and any engineered features) and output variables (yield predictions), as shown in **Figure 2**. The network comprises the following components. The input layer takes the NDVI values and any additional engineered features. One or more hidden layers processing these inputs and learning complex patterns. An output layer that predicts crop yield in kilograms per acre based on input data. The hidden layers capture the relationships between NDVI and yield by learning weight parameters that help transform the input into meaningful predictions. The structure and flow of the neural network, as depicted in **Figure 2**, visually represent how input data are processed through layers to generate yield predictions.

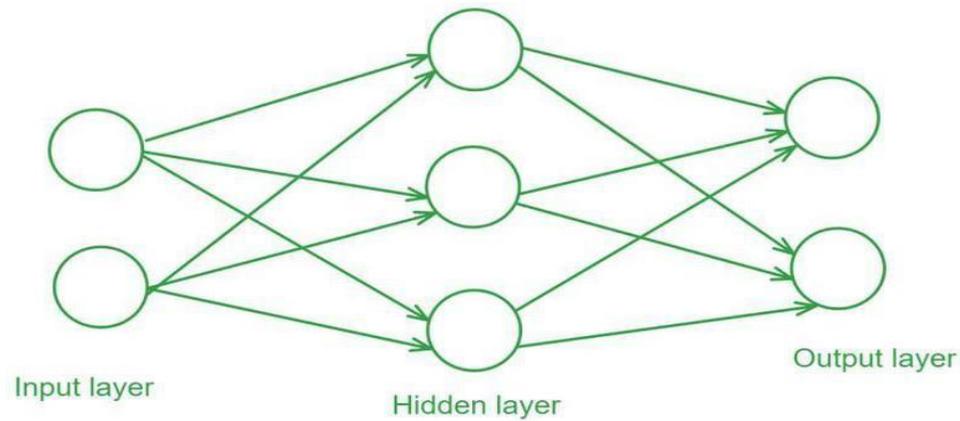


Figure 2. Feedforward neural network architecture

Testing and Prediction

For Model Evaluation and Testing, the trained model was assessed by providing a single RGB image of a farm, and the model then predicted the corresponding crop yield. This evaluation method was used to determine the model's ability to generalize to new data and its practical application in real-world farming scenarios.

FINDINGS AND DISCUSSION

Comprehensive Evaluation of Model Performance: Key Metrics and Visualizations to Improve Yield Prediction Accuracy

Mean Squared Error (MSE)

Definition: The mean squared error (MSE) is a statistical measure that quantifies the average squared difference between predicted and actual values. It is commonly used to assess the accuracy of predictive models. The MSE equation is given as

$$MSE = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2 \dots (2)$$

n : Total number of observations in the dataset, indicating how many actual and predicted values were considered.

y_i : Actual value (ground truth) of dependent variable for the i th observation, such as measured yield.

\hat{y}_i : Predicted value of dependent variable for the i th observation, derived from regression model or prediction algorithm.

$(y_i - \hat{y}_i)^2$: Squared error for each observation, ensuring that the error is positive to prevent cancelation of differences.

$\sum_{i=1}^n$: Notation indicating the summation of squared errors across all observations from $i=1$ to n , accumulating the squared differences.

The MSE method emphasizes larger errors more than smaller ones because the differences are squared. Therefore, it is particularly sensitive to outliers. A lower MSE value indicates better model performance; an MSE value of zero indicates perfect predictions. In this study, the calculated MSE was 46,143,804.2462, suggesting the average squared error across all yield predictions.

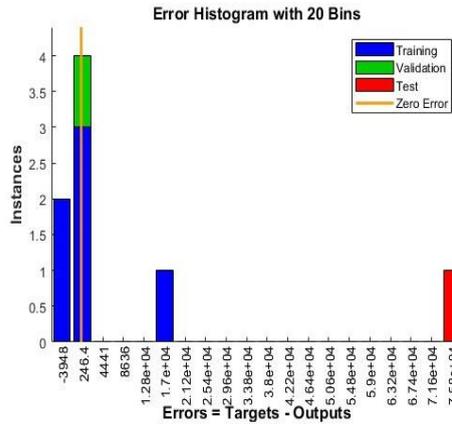


Figure 3. Error Histogram

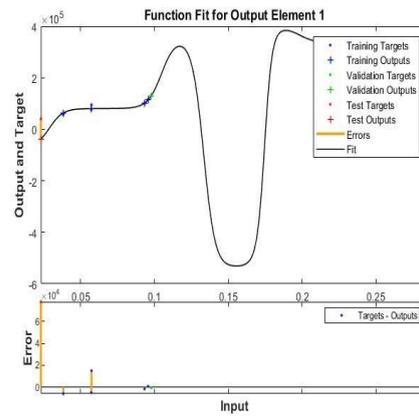


Figure 4. Plot fit

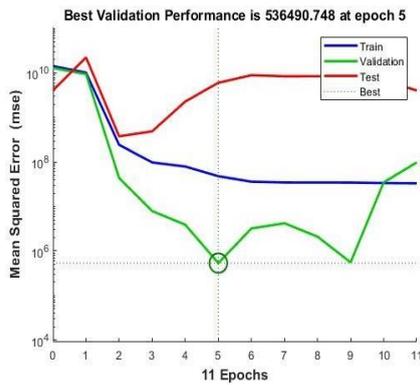


Figure 5. Plot train state

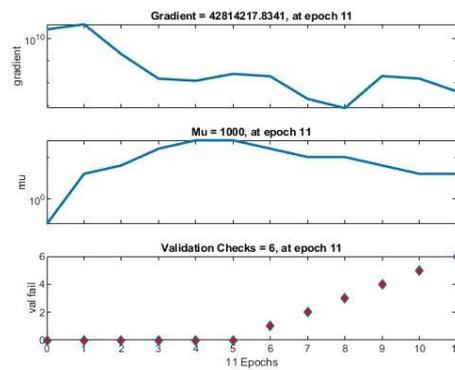


Figure 6. Plot train state

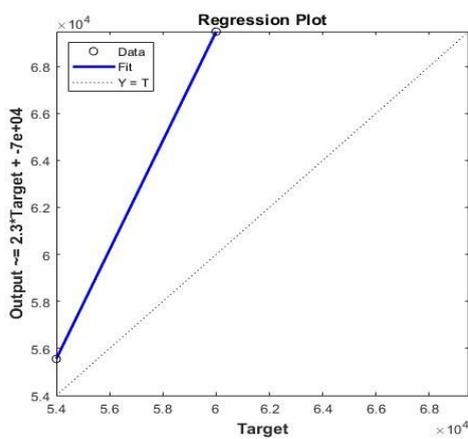


Figure 7. Regression Plot

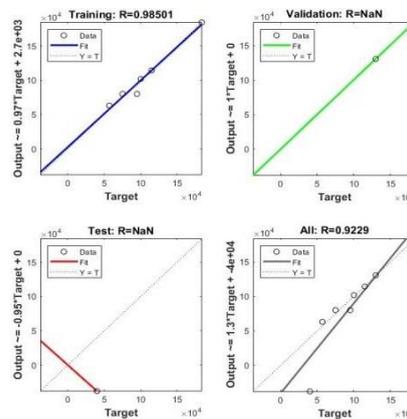


Figure 8. Final Regression Results

As shown in Figure 3, the error histogram displays the distribution of prediction errors across the training (blue), validation (green), and test (red) datasets. The majority of errors were concentrated around zero, indicating that the model provided accurate yield predictions for most data points. However, a slight spread in the test set errors suggests some variability when the model encounters unseen farm images, possibly due to NDVI variations or inconsistencies in the collected

yield data. This distribution helps assess how well the model generalizes to new sugarcane farm data, making it critical for evaluating the overall predictive performance.

As depicted in Figure 4, this plot shows the relationship between the predicted and actual yield data across various data points. The curve highlights the model's ability to fit the training and validation data. Deviations from the ideal fit line may indicate regions where the model is struggling, such as complex NDVI patterns within the orthophoto or outlier yield data. Understanding this fit is crucial for identifying where improvements, such as data preprocessing or model tuning, can enhance prediction accuracy, particularly for more challenging datasets.

In Figure 5, the performance plot shows the mean squared error (MSE) for the training (blue), validation (green), and test (red) datasets over the course of 11 epochs. The model achieved its best validation performance at epoch 5, as evidenced by the lowest MSE value at that point. The validation error then begins to increase while the training error continues to decline, indicating overfitting beyond this point. This plot is essential for determining the optimal stopping point in training to ensure that the model does not memorize the training data at the expense of generalization to new sugarcane farms, thus maintaining a balance between accuracy and overfitting.

As shown in Figure 6, this diagram tracks key training states, including the gradient, Mu parameter, and validation checks. The gradient steadily decreased, indicating that the model was converging as training progressed. The Mu parameter (used in the Levenberg-Marquardt algorithm) decreased, indicating that the optimization process effectively fine-tuned the model. The limited number of validation checks suggests that the model avoids frequent failures on the validation set, thus stabilizing training without significant overfitting. Monitoring these training states is crucial for ensuring smooth optimization and generalization, especially when predicting yield based on complex NDVI and ortho photo data.

As shown in Figure 7, the regression plot compares the predicted yield values (y-axis) with the actual yield data (x-axis). The majority of data points align closely with the diagonal line, indicating a strong correlation between the predicted and actual yield values. The regression line, with a slope near 1, confirms the model's ability to generalize well across different sugarcane farm data. This close agreement highlights the model's robustness in capturing the relationship between the NDVI values from orthophotos and the corresponding farm yield data, making it highly reliable for yield prediction tasks.

As illustrated in Figure 8, the final regression results for the training, validation, and test datasets show a strong linear relationship between the predicted and actual yield values. Each subplot demonstrates the model's ability to generalize across different datasets, with predictions closely matching actual yields. The overall R-value of 0.9921 indicates that the model explains nearly all variance in the yield data. This strong predictive performance confirms that the feedforward network trained on NDVI values and orthophotos is highly effective at estimating yield data across various sugarcane farms.

CONCLUSIONS

This study successfully developed a predictive model that leverages RGB images captured by drone technology to estimate crop yield. By converting these images into multispectral representations using Generative Adversarial Networks (GANs) and calculating the Normalized Difference Vegetation Index (NDVI), we integrated the NDVI data with yield information sourced from farmers. The model was trained and evaluated using various performance metrics, resulting in a mean square error (MSE) of 46,143,804.2462 and a root mean square error (RMSE) of approximately 6792.92 kg/acre. The model's performance was illustrated through multiple visualizations, including error histograms, regression plots, and training performance metrics,

demonstrating its effectiveness in predicting yields based on the input data. Future research can explore several pathways to enhance the model's accuracy and applicability. Investigating advanced machine learning techniques, such as ensemble methods and cutting-edge deep learning architectures, may yield improved prediction accuracy. Additionally, integrating more diverse datasets, which encompass varying climatic conditions and soil types, would allow the model to be better generalized across different agricultural contexts. Further studies could also focus on real-time yield estimations using temporal datasets, enabling more responsive agricultural management practices to adapt to changing conditions.

LIMITATION & FURTHER RESEARCH

Limitations of the Study

1. *High Initial Costs:* The adoption of drone technology and machine learning-based tools, such as Generative Adversarial Networks (GANs), can be financially prohibitive for small-scale farmers due to the cost of equipment and computational resources.
2. *Data Requirements:* The model's accuracy depends heavily on a comprehensive and diverse dataset. In this study, the dataset was limited to specific geographical regions and climatic conditions, which may hinder generalizability.
3. *Model overfitting:* Performance metrics, such as Mean Squared Error (MSE), suggest potential overfitting during training. This can affect the model's ability to generalize to unseen data.
4. *Spectral Fidelity Challenges:* While CGANs produce high-quality multispectral images, ensuring high fidelity across all spectral bands remains a challenge, particularly in complex agricultural scenarios.
5. *Operational Challenges:* Regular drone flights and the associated logistical efforts, including consistent weather and timing, increase operational complexity.
6. *Limited Real-Time Application:* The current approach focuses on postprocessing captured images, which delays real-time decision-making.
7. *Dependency on NDVI:* Although NDVI is a strong indicator, relying solely on it may oversimplify complex crop conditions, such as soil fertility and pest infestations.

Suggestions for Future Research

1. *Expanding Dataset Diversity:* We incorporate data from various climatic zones, soil types, and farming practices to improve the model's adaptability and robustness.
2. *Real-Time Data Processing:* Develop real-time drone data processing and multispectral conversion systems for more immediate agricultural interventions.
3. *Ensemble Learning Techniques:* This study investigates advanced machine learning techniques, like ensemble methods, to reduce prediction errors and enhance robustness.
4. *Integration of Other Indices:* NDVI should be combined with other vegetation indices, such as SAVI (Soil-Adjusted Vegetation Index) or EVI (Enhanced Vegetation Index), for more comprehensive analysis.
5. *Economic feasibility studies:* This section assesses the cost-effectiveness and potential subsidies required for deploying such technologies in resource-constrained settings.
6. *Improving GAN Architectures:* Explore innovative GAN frameworks, such as VAE-GAN hybrids or multi-code GANs, to enhance the spectral accuracy and robustness of RGB-to-multispectral conversion.
7. *Dynamic environmental monitoring:* This approach incorporates temporal datasets that account for changes in weather patterns, water availability, and pest outbreaks to realize adaptive predictions.
8. *Automating model updates:* Continuous learning pipelines are implemented to update models as new data are acquired, ensuring relevance and accuracy over time.
9. *Integration with IoT Systems:* Combine drone imaging with Internet of Things (IoT) sensors for a holistic approach to precision agriculture, including monitoring of moisture and nutrient contents.

10. *Policy and Adoption Studies*: Conduct studies on farmer adoption, policy frameworks, and training programs to facilitate the wider implementation of these technologies.

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